



成長する組織の力学過程
Mechanical control of
epithelial pattern formation

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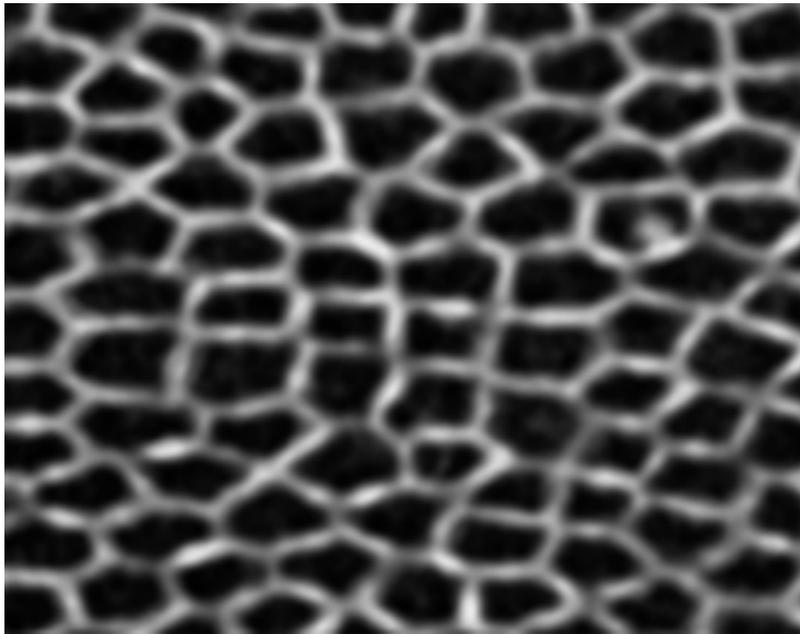
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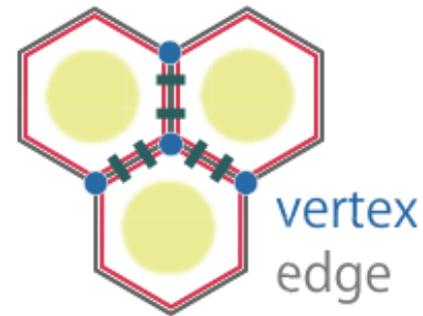
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Pressure of a cell and tension of an edge



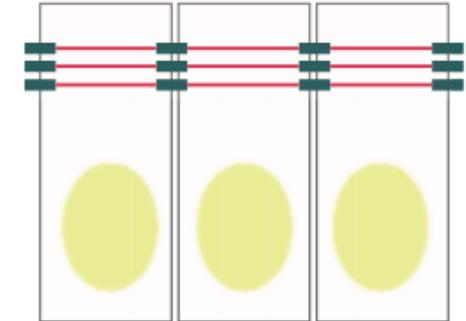
10 μm 1 min interval Replay: 15 fps

A top view of an epithelial sheet



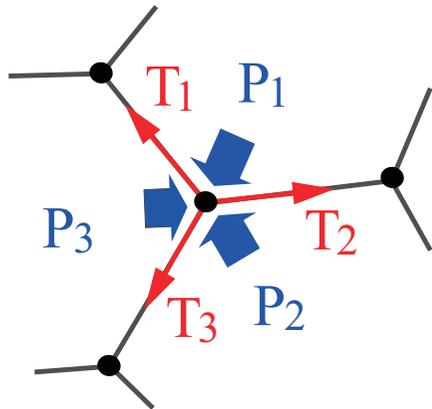
Myosin,
Cortical actin cable

A side view of an epithelial sheet

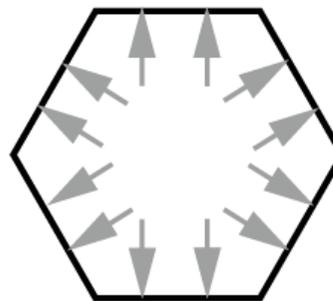


Cadherin

Balance of forces
at each vertex

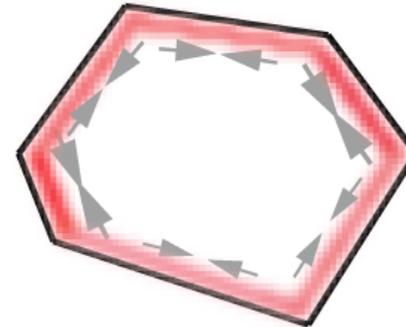


Pressure



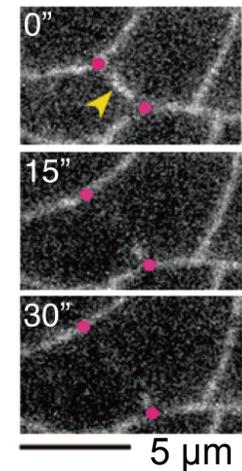
Cytoplasm,
microtubule

Tension



Myosin, Cortical
actin, Cadherin

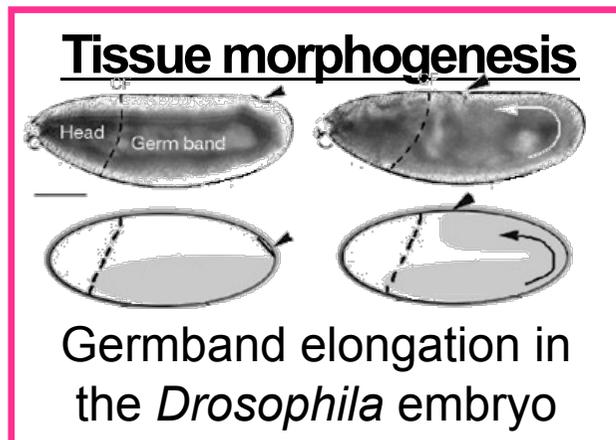
Cut an edge!



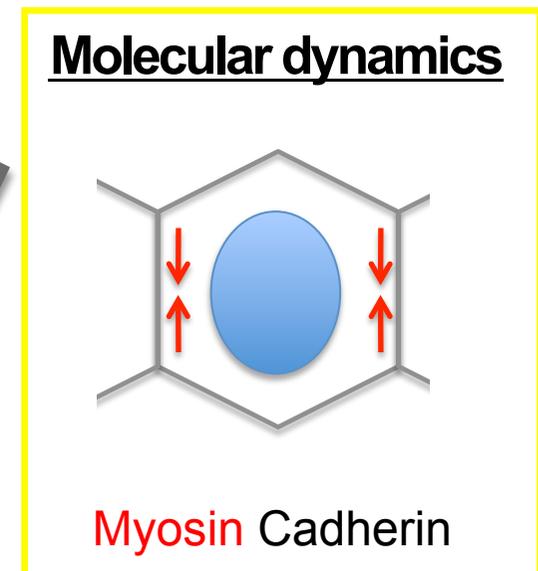
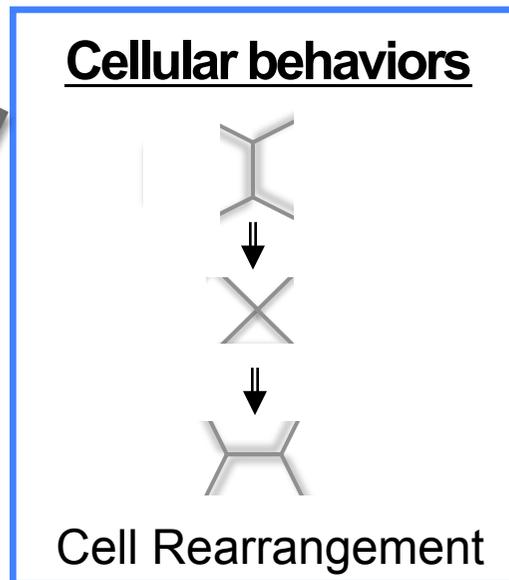
Questions

Morphology \Leftrightarrow *Mechanical force*

1. How does mechanical force that drives tissue deformation emerge in light of the molecular properties of the constituent cells?
2. How does the generated forces regulate the correct patterning of a tissue?

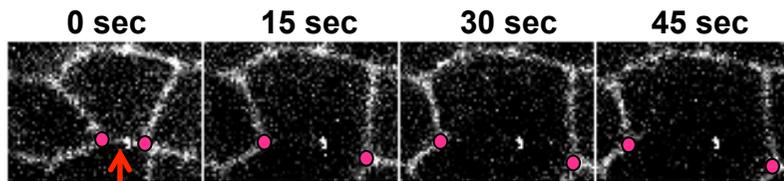


Bertret et al. (2004)



Measuring dynamics of forces *in vivo* is very difficult

A relative value of tension measured by laser cutting



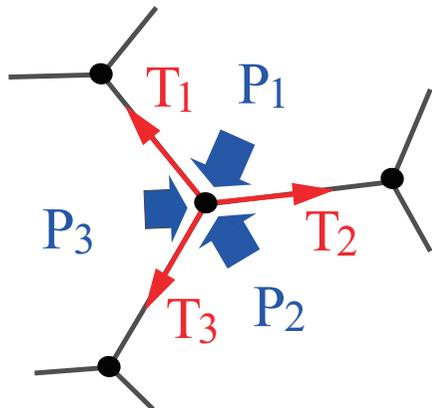
Destroy cortical actin network

“invasive”

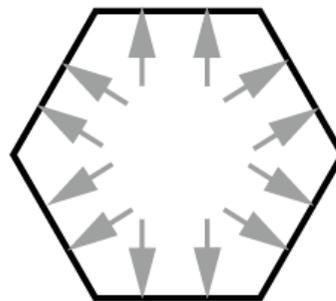
Vertices move faster \Rightarrow Larger tension

No appropriate method to directly and repeatedly measure forces in a multi-cellular tissue

Balance of forces at each vertex

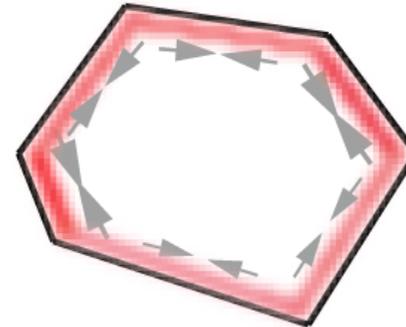


Pressure



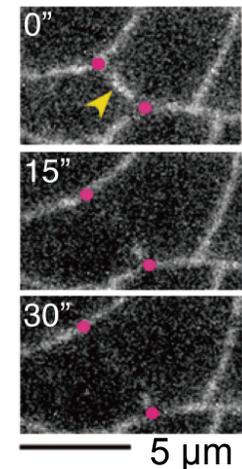
Cytoplasm, microtubule

Tension



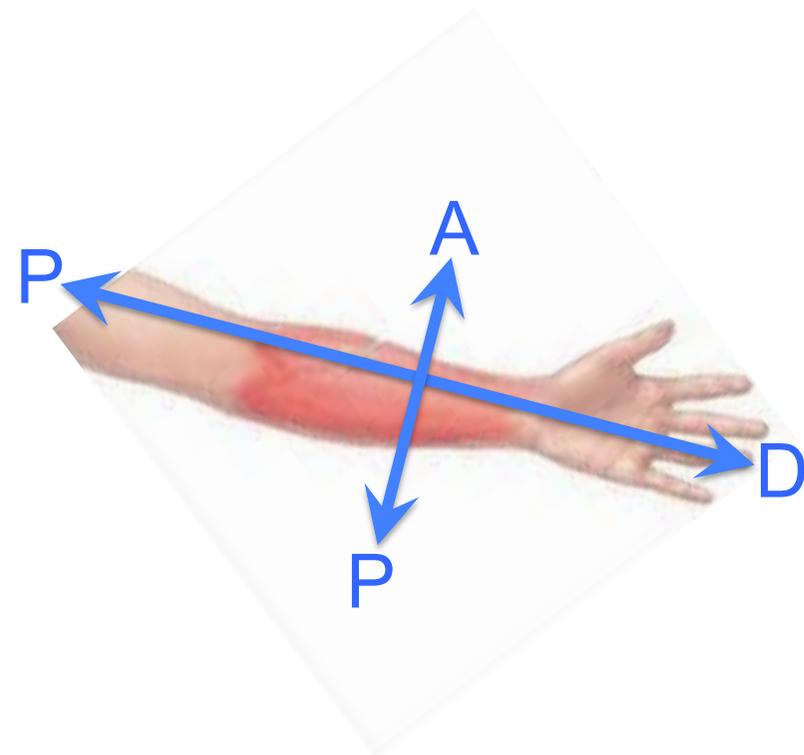
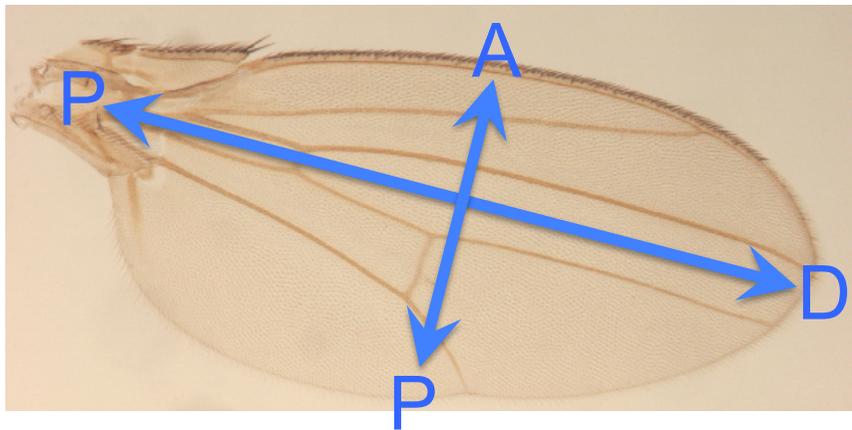
Myosin, Cortical actin, Cadherin

Cut an edge!



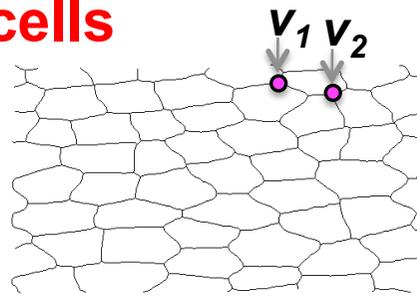
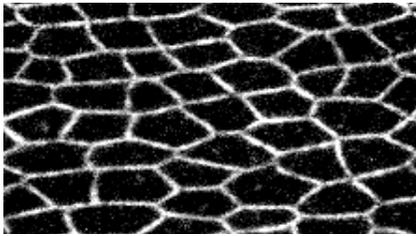
Outline

1. Our new method to estimate forces
2. Forces in the *Drosophila* wing
3. How forces regulate epithelial pattern formation



Outline of our new method to estimate forces

Input: image of cells



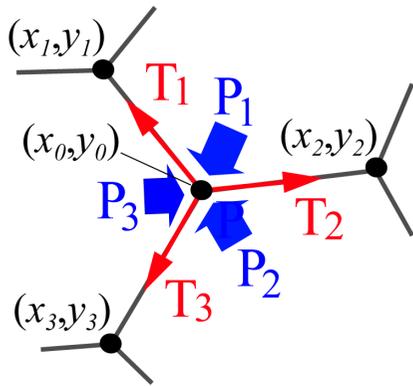
position of vertex

$$v_1(x_1, y_1),$$

$$v_2(x_2, y_2),$$

conditions
< unknowns

balance of forces at each vertex



$$\alpha_x^1 T_1 + \alpha_x^2 T_2 + \alpha_x^3 T_3 + \beta_x^1 P_1 + \beta_x^2 P_2 + \beta_x^3 P_3 = \gamma \dot{X}_0$$

$$\alpha_y^1 T_1 + \alpha_y^2 T_2 + \alpha_y^3 T_3 + \beta_y^1 P_1 + \beta_y^2 P_2 + \beta_y^3 P_3 = \gamma \dot{Y}_0$$

$$T_1^x = \frac{x_1 - x_0}{\|\vec{x}_1 - \vec{x}_0\|} \times T_1 \quad P_1^x = \frac{y_2 - y_1}{2} \times P_1$$

$$A\vec{p} = \gamma\vec{V}$$

pressure & tension drag

$$\vec{p} = (T_1, \dots, T_M, P_1, \dots, P_N)$$

$$\vec{V} = \dot{\vec{x}}$$

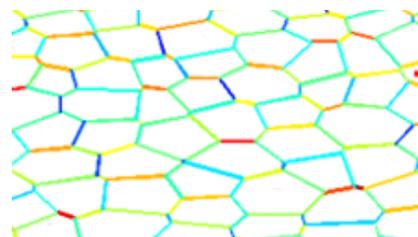
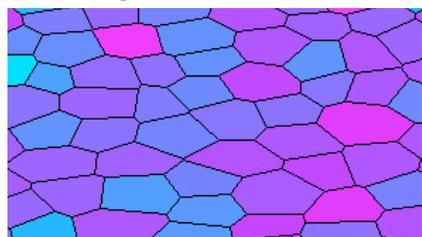
Inverse problem

“ minimize
 $F = |Ap - \gamma V|^2 + \mu |Bp - f|^2$ ”

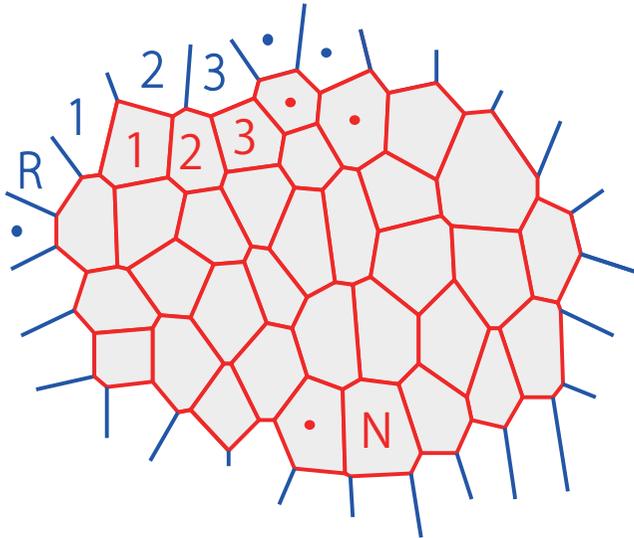
μ is determined
 by Bayesian
 statistics

Expected
 features
 of system
 ||
 Positive
 tension

Output: “relative” values of forces



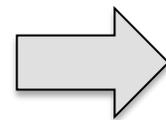
Indefiniteness and its physical interpretation



- $N+R$ cells, $v+R$ vertices, and $M+2R$ edges
- If all vertices are 3-way junction, $M=(3/2)v$
- Note Euler's theorem $v-M+N=1$

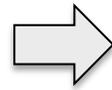
Conditions: (num. of vertex) $\times 2 = 2(v+R)$

Unknowns: (num. of cell + edge) = $M+N+3R$



$R+1$ indefiniteness

■ I indefiniteness by hydrostatic pressure



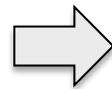
Estimate **relative values** of forces

$$A\bar{p}_{iso} = 0,$$

$$\bar{p}_{iso} = (0, \dots, 0, 1, \dots, 1)$$

$$P_i = cp_i + p_{hs}, T_j = ct_j$$

■ R indefiniteness by boundary condition



Becomes less significant as N increases

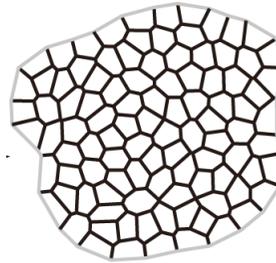
True and estimated forces in artificial data

Numerical simulation :

$$U = \sum_{\text{Cell:}i} U_e(A_i) + \sum_{\text{Contact:}j} U_a(l_j) + \sum_{\text{Cell:}i} U_c(L_i)$$

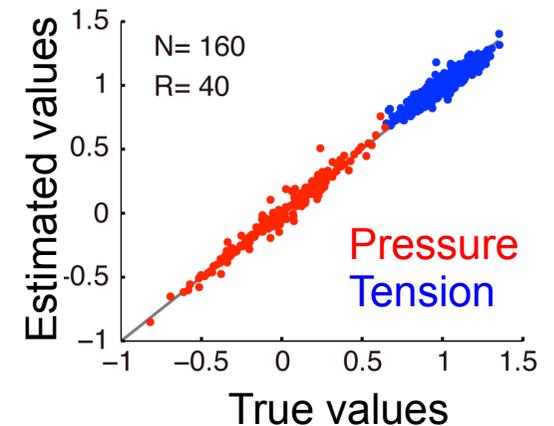
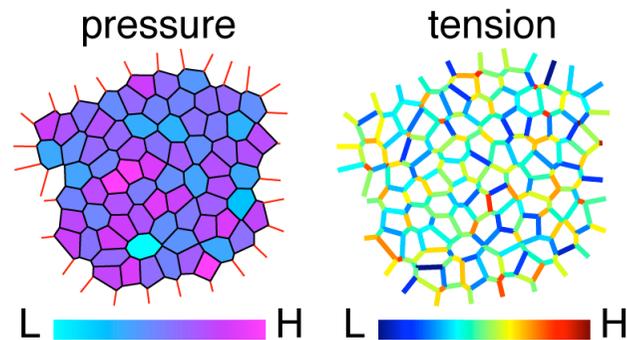
Area elasticity Cell adhesion, Contraction Cortical elasticity

係数を振る



Calculate true values of forces

Estimation :



※ The prior (positive tension) that we adopted yielded the best results among priors tested (e.g. L2-norm, spatial smoothness).

Advantages of our new method

Input: **image of cells**



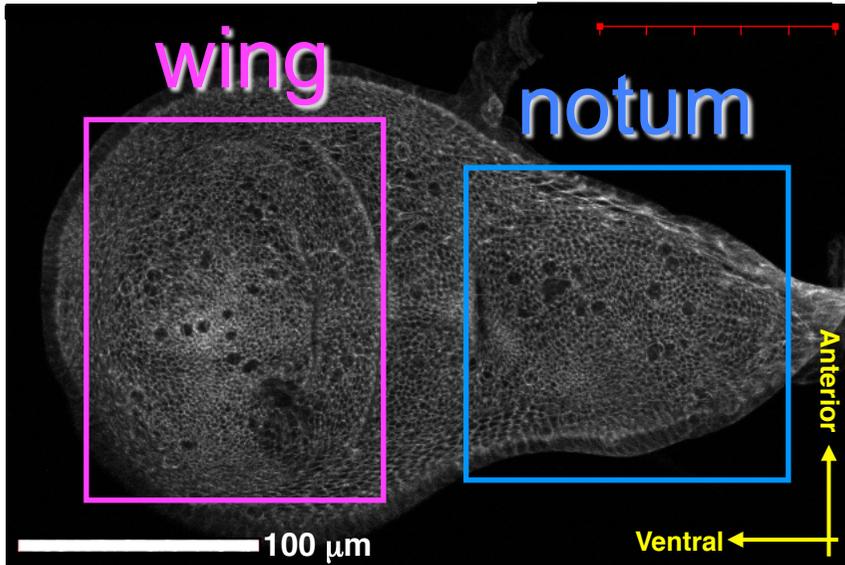
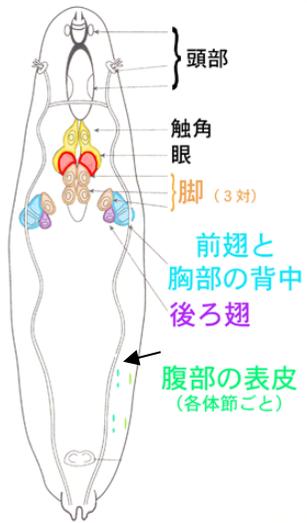
Output: **distribution of forces**

- **Single cell resolution**
- **Applicable to a tissue-scale**
- **Noninvasive**
- **No assumption of forms of the potential energy**

Drosophila epithelial tissues (notum and wing)

Larva

Wing disc of *Drosophila* 3rd instar larva



Embryo



<http://flybase.org/>

Adult

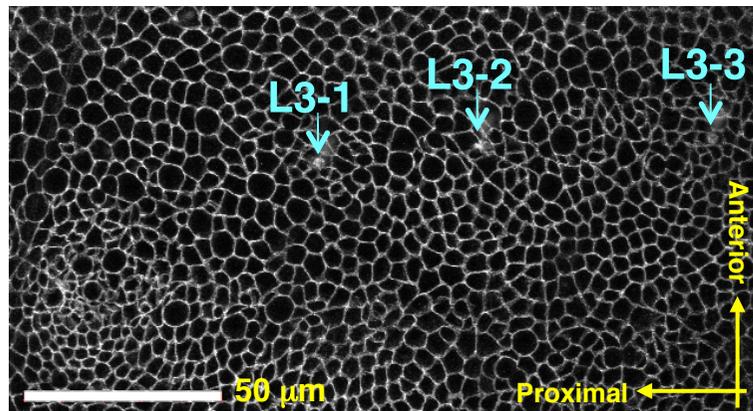


Wing



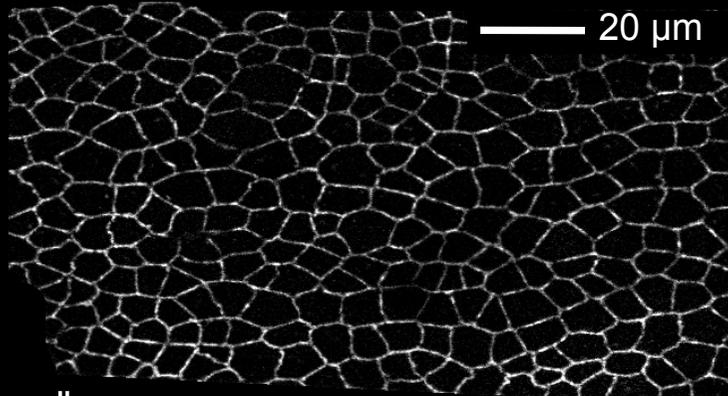
Pupa

Wing at 15.5 hr APF (after puparium formation)

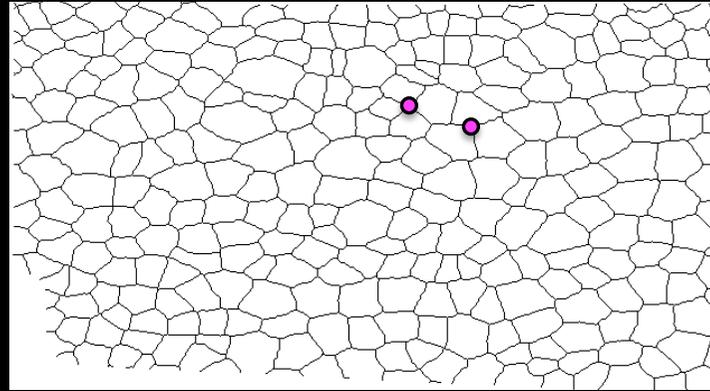


Application to the *Drosophila* pupal wing

Input: image of cells



get positions of vertices



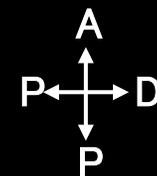
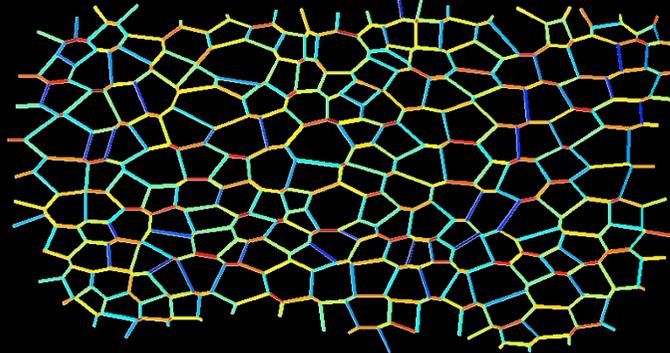
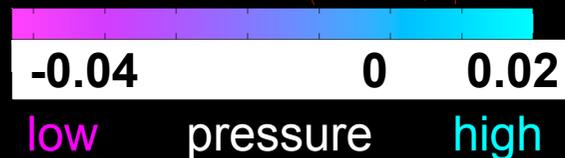
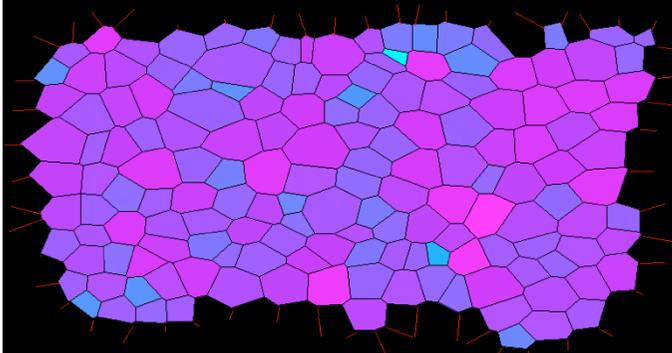
$$v_a(x_a, y_a), \\ v_b(x_b, y_b),$$

balance of forces at each vertex

$$A\vec{p} = \gamma\vec{V} \quad \vec{p} = (T_1, \dots, T_M, P_1, \dots, P_N) \quad + \quad \text{Bayesian formulation}$$

pressure & tension drag

Output: “relative” values of forces



The summary of results

1. Our new method to estimate forces

2. Forces in the *Drosophila* wing

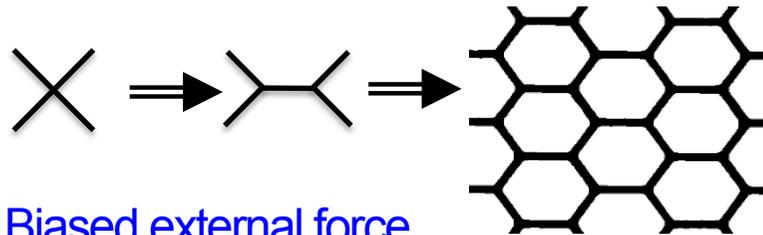
- stronger tension along the PD axis
- nature of tension: external force stretching the wing
- "force-generating" and "force-responding" properties of myosin

3. How forces regulate epithelial pattern formation

- hexagonal packing in the wing and notum
- more strongly biased tensile force -> more hexagons?
- biased external force accelerates hexagonal pattern formation both *in silico* and *in vivo*

Anisotropic external force instructs directional arrangement of cells for efficient hexagonal packing

Anisotropic stretch



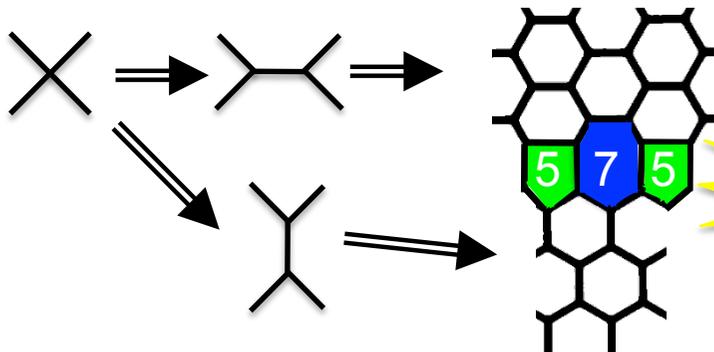
Biased external force

Aligned!!

Anisotropic tensile forces may avoid the mismatch in orientations of small group of cells by setting the unique axis of cell rearrangement.

Faster relaxation of the energy

Control and isotropic expansion



Mismatch!!

This mismatch in orientations of small group of cells produces non-hexagonal cells.

Slower relaxation of the energy

Mechanical basis of pattern formation: feedback regulations that connects molecular, cellular, and tissue dynamics

