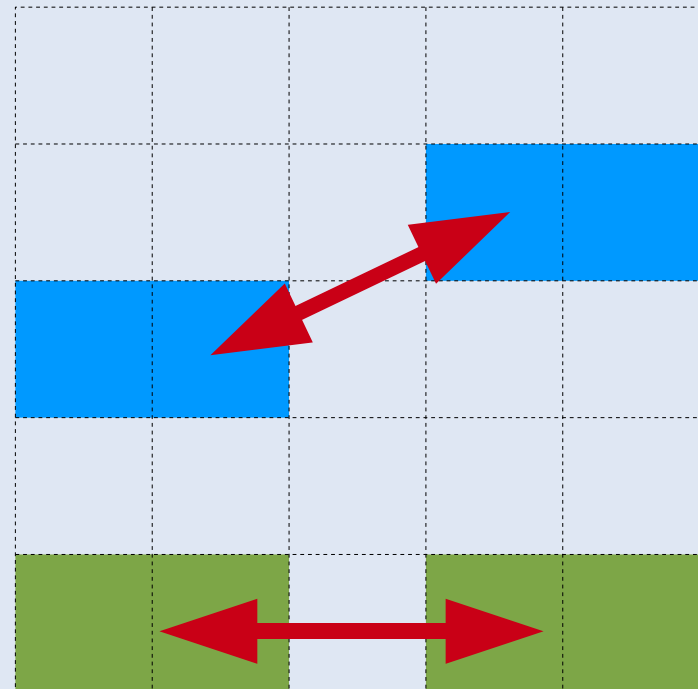


# Observational Reinforcement Learning

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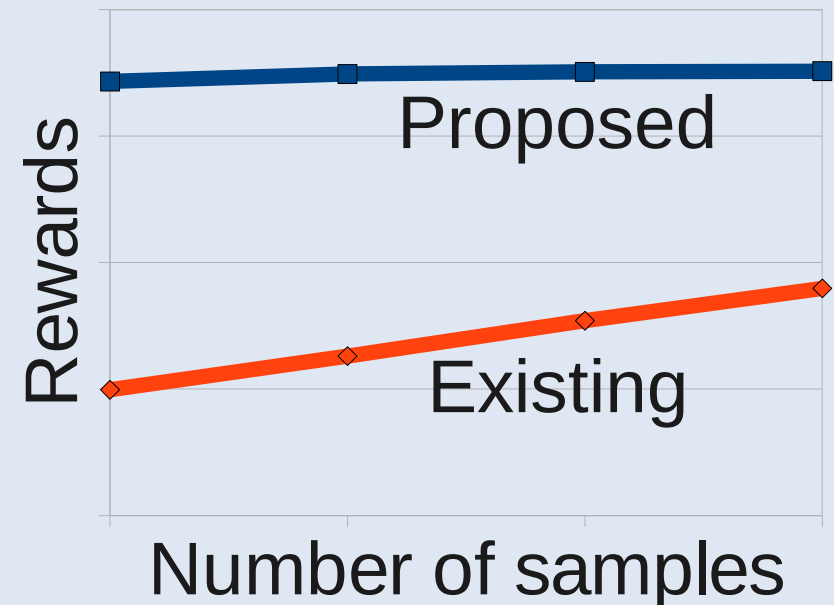
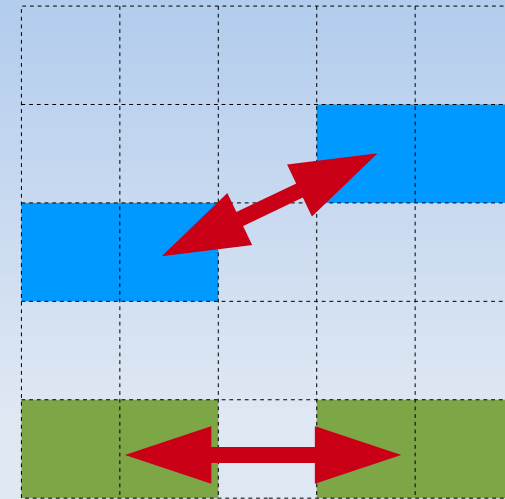
- **Goal of RL:** finding the policy maximizing the rewards in **unknown** environments.
- **Current shortcoming:** **too many** samples are needed to find good policies.
- **Proposed idea:** share data between **similar** regions based on additional **observations**.



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- **Solution:** apply **multitask learning** to similar regions.
- Application of ORL to object lifting task



- **Come to my poster!**